

# F2S-Type Torque Arm

## Fixing a Reducer and a Torque Arm

- 1 Torque arms are subjected to rotation reaction torque, therefore, they must be strong by using materials of enough thickness and bolts to endure the shock load on starting/braking. Choosing our optional torque arms is the most appropriate solution. (Refer to page E85.)
- 2 When installing a reducer with a torque arm, be sure to tighten the bolt using helical spring lock washers and plain washers. For proper tightening torque, refer to the table shown on the right.

Bolt Size and Respective Tightening Torque

Bolt Size	Tightening Torque N·m { kgf·m }
M6	4.9 { 0.5 }
M8	13 { 1.3 }

## How to fix the Torque Arm Fixing Part

### 1 In case of Normal/Reverse Operation

Firmly fix the fixing part of the torque arm. Make sure that there is no radial load (suspending load) imposed between the driven shaft and the hollow shaft of the reducer, caused by poor alignment between the hole of fixing part and the connecting machine. (Refer to the Figure-6)

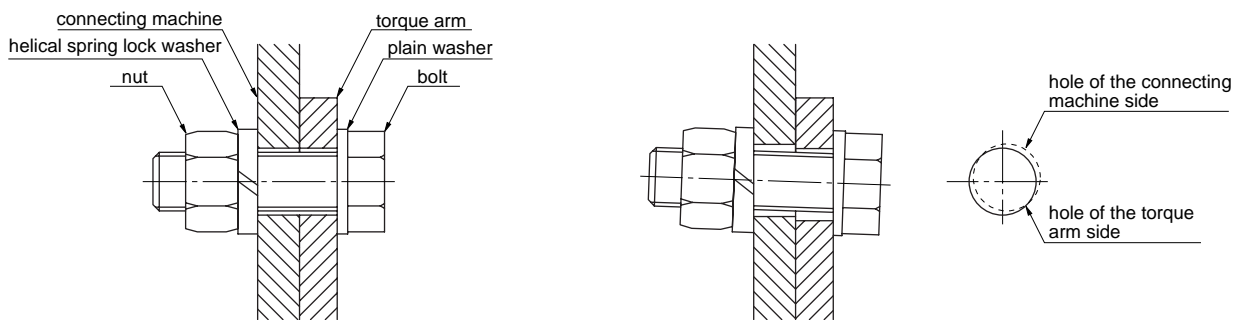


Figure-6 Attaching the fixing part

Excess force arisen in the driven shaft and the hollow shaft may cause failure of the machine.

### Bad example

**Note** ) When a backlash in the attaching part arose by normal/reverse operations or by high frequency of starting/stopping, the intense impact given to the torque arm in each starting may cause the failures such as loosening of the tightening bolt.

### 2 In case of One-Direction Operation

If the frequent starting torque like in the normal / reverse operation, is not observed, operation with the released fixing part of torque arm is possible. However, it is necessary to fix the driven shaft and the hollow shaft. (Refer to page E80 ~ E81, Figure -2 ~ Figure-4)

In this case, be sure to secure enough space both for radial direction and for thrust direction in the alignment between the connecting machine and the fixing part.

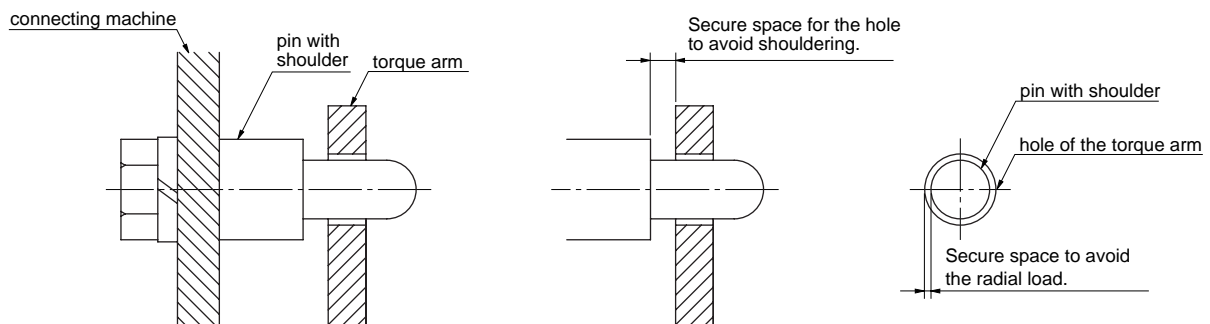
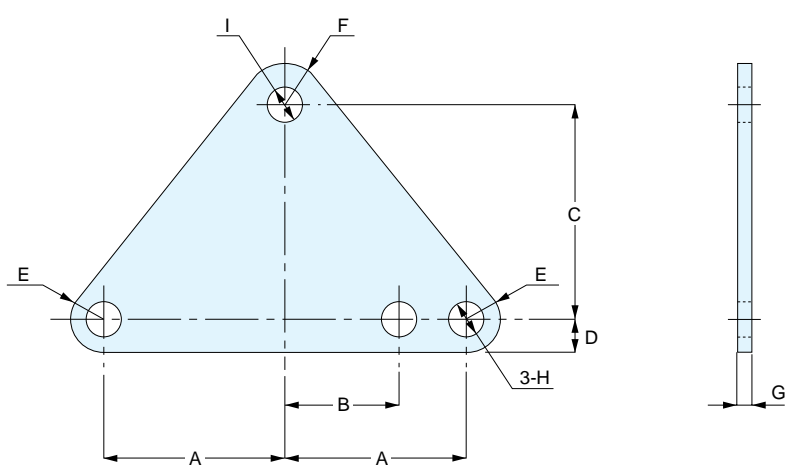


Figure-7 Example of using pin with shoulder

- Parallel Shaft Performance Table/ Dimension
- Gearmotor with Brake
- Water-resistant Gearmotor with Brake
- Speed Control Gearmotor
- Gearmotor with Clutch / Brake
- GT-Type Gearmotor with Brake
- Right Angle Shaft Performance Table/ Dimension
- Gearmotor with Brake
- With Water-resistant Brake Motor
- Speed Control Gearmotor
- Concentric Hollow Shaft Concentric Solid Shaft Performance Table Dimension
- Gearmotor with Brake
- With Water-resistant Brake Motor
- Speed Control Gearmotor
- Parallel Shaft GTR-L Series Performance Table/ Dimension
- Reversible Gearmotor with Brake
- Speed Control Gearmotor with Brake
- Technical Information
- Standard Motors
- Cautions for Safety
- Option

## FS Type (Hollow Shaft) · Torque Arm (Option)



Model Number	Frame Number	A	B	C	D	E	F	G	H	I
TAF2S-12	12	43	24	37.5	7	R7	R9	3.2	8.4	7
TAF2S-15	15	48	30	56.5	9	R9	R11	3.2	10.5	9

## Designing the Torque Arm

In case customer does not use our optional torque arm and use their manufactured torque arm as shown in the Figure-8, the distance between the center of the output shaft and the fixing point(r) can be calculated with the following formulas:

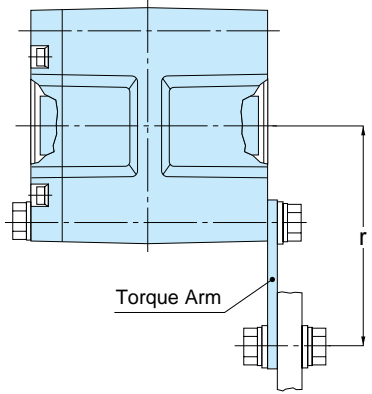
SI Unit

$$r(\text{mm}) = \frac{\text{Actual load torque}(\text{N}\cdot\text{m}) \times 1000}{\text{Allowable O.H.L.}(\text{N}) - 9.8 \times \text{Mass of the reducer}(\text{kg})}$$

Gravimetric Unit

$$r(\text{mm}) = \frac{\text{Actual load torque}(\text{kgf}\cdot\text{m}) \times 1000}{\text{Allowable O.H.L.}(\text{kgf}) - \text{Weight of the reducer}(\text{kgf})}$$

Figure-8



Note ) For the thickness of torque arm, Please refer to above Torque Arm. (Option)

In case of using the torque arm as shown in the Figure-9, the distance between the center of the output shaft and the fixing point(r) can be calculated with the following formulas:

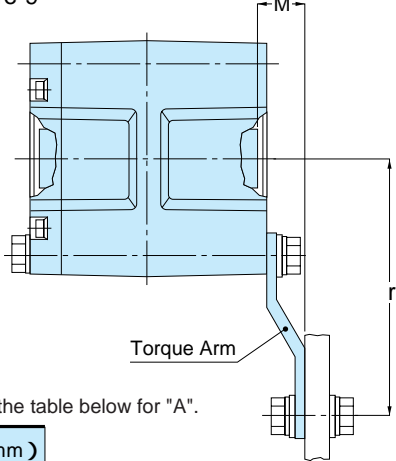
SI Unit

$$r(\text{mm}) = \frac{\text{Actual load torque}(\text{N}\cdot\text{m}) \times (A + M) \times 1000}{\{\text{Allowable O.H.L.}(\text{N}) - 9.8 \times \text{Mass of the reducer}(\text{kg})\} \times (A + 10)}$$

Gravimetric Unit

$$r(\text{mm}) = \frac{\text{Actual load torque}(\text{kgf}\cdot\text{m}) \times (A + M) \times 1000}{\{\text{Allowable O.H.L.}(\text{kgf}) - \text{Weight of the reducer}(\text{kgf})\} \times (A + 10)}$$

Figure-9



Note ) Refer to the table below for "A".

Frame Number	A (mm)
12	43
15	55

Parallel Shaft Performance Table/ Dimension

- Gearmotor with Brake
- Water-resistant Gearmotor with Brake
- Speed Control Gearmotor
- Gearmotor with Clutch / Brake
- GT-Type Gearmotor with Brake

Right Angle Shaft Performance Table/ Dimension

- Gearmotor with Brake
- With Water-resistant Brake Motor
- Speed Control Gearmotor

Concentric Hollow Shaft Concentric Solid Shaft Performance Table/ Dimension

- Gearmotor with Brake
- With Water-resistant Brake Motor
- Speed Control Gearmotor

Parallel Shaft GTR-L Series Performance Table/ Dimension

- Reversible Gearmotor with Brake
- Speed Control Gearmotor with Brake

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