

# FS·F3S-Type Torque Arm

## Fixing a Reducer and a Torque Arm

- 1 Torque arms are subjected to rotation reaction torque, therefore, they must be strong by using materials of enough thickness and bolts to endure the shock load on starting/braking. Choosing our optional torque arms is the most appropriate solution. (Refer to page E61.)
- 2 When installing a reducer with a torque arm, be sure to tighten the bolt using helical spring lock washers and plain washers. For proper tightening torque, refer to the table shown on the right.

Bolt Size and Respective Tightening Torque

Bolt Size	Tightening Torque N·m { kgf·m }
M5	2.9 { 0.3 }
M6	4.9 { 0.5 }
M8	13 { 1.3 }
M10	25 { 2.6 }
M12	44 { 4.5 }
M14	69 { 7.0 }
M16	108 { 11 }
M20	294 { 30 }

## How to fix the Torque Arm Fixing Part

- 1 In case of Normal/Reverse Operation  
Firmly fix the fixing part of the torque arm. Make sure that there is no radial load (suspending load) imposed between the driven shaft and the hollow shaft of the reducer, caused by poor alignment between the hole of fixing part and the connecting machine. (Refer to the Figure-6)

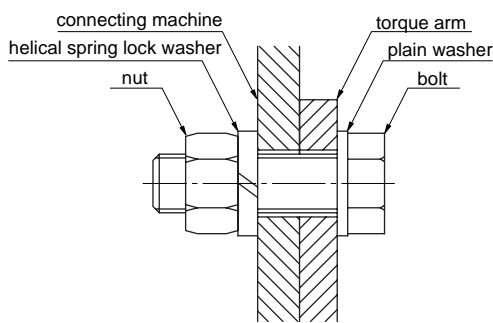
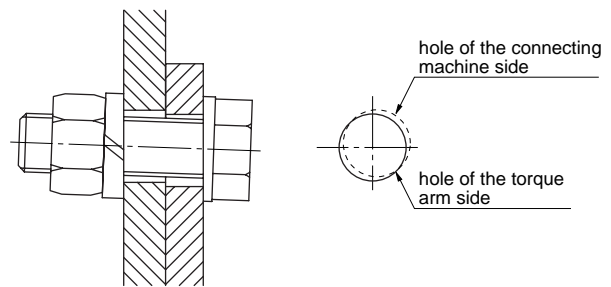


Figure-6 Attaching the fixing part



Bad example

**Note** ) When a backlash in the attaching part arose by normal/reverse operations or by high frequency of starting/stopping, the intense impact given to the torque arm in each starting may cause the failures such as loosening of the tightening bolt.

- 2 In case of One-Direction Operation  
If the frequent starting torque like in the normal/reverse operation, is not observed, operation with the released fixing part of torque arm is possible. However, it is necessary to fix the driven shaft and the hollow shaft. (Refer to page E56 ~ E-57, Figure -2 ~ Figure-4)  
In this case, be sure to secure enough space both for radial direction and for thrust direction in the alignment between the connecting machine and the fixing part.

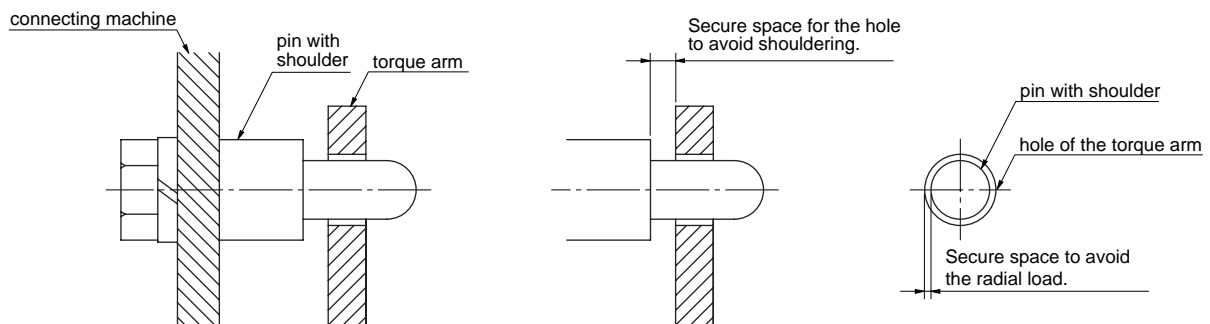


Figure-7 Example of using pin with shoulder

- Parallel Shaft (Performance Table/Dimension)
- Gearmotor with Brake
- Water-resistant, Outdoor Gearmotor with Brake
- Gearmotor with Clutch/Brake
- Reducer (Double Shaft)
- S-Type Reducer
- Right Angle Shaft (Performance Table/Dimension)
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- Technical Information
- Standard Motors
- Cautions for Safety
- Option
- GT-STEP Index Gearmotor
- KOMPASS Gearbox

FS Type (Hollow Shaft) • Torque Arm (Option)

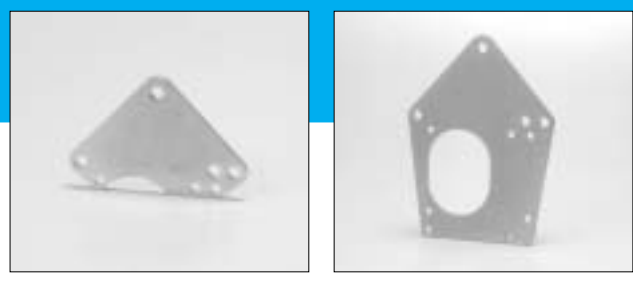


Figure No. 1

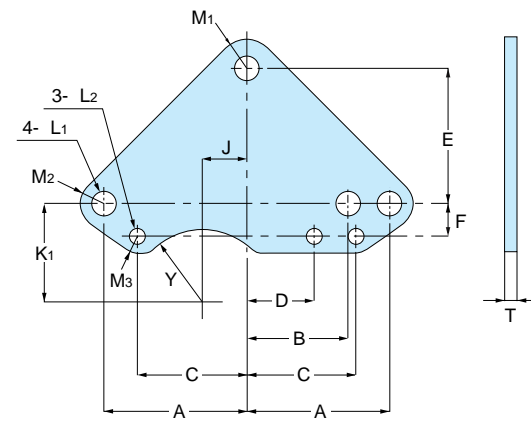
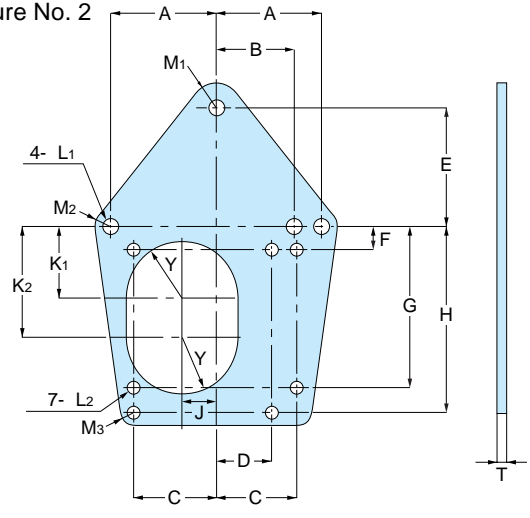


Figure No. 2



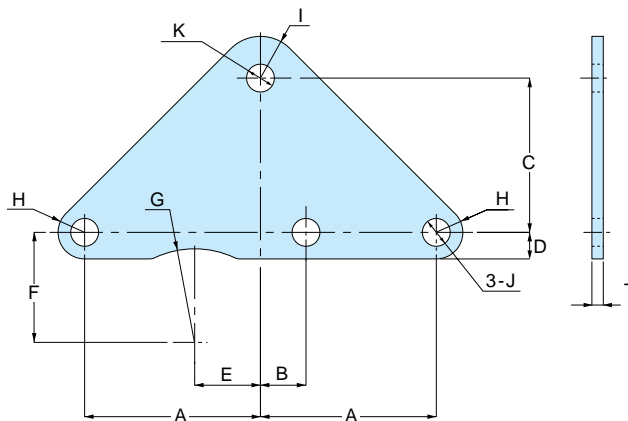
Model Number	Frame Number	Figure No.	A	B	C	D	E	F	G	H	J	K <sub>1</sub>	K <sub>2</sub>	L <sub>1</sub>	L <sub>2</sub>	M <sub>1</sub>	M <sub>2</sub>	M <sub>3</sub>	Y	T
TA-20	20	1	55	39	42	26	52	13			17	38		9	5.5	R11	R 9	R 6	R28	4.5
TA-25	25	1	63	47	47	31	61	16			19	44		11	6.5	R15	R10.5	R 7	R34	4.5
TA-30	30	1	70	52	53	35	70	17			20	50		11	9	R15	R12	R 9	R39	6
TA-35	35	2	82	62	64	44	94	18	126	146	26	56	88	13	9	R18	R12	R10	R43.5	6
TA-45	45	2	102	72	80	50	110	22	152	182	32	70	104	15	11	R20	R15	R11	R51	9
TA-55	55	2	129	93	97	61	160	32	190	226	39	90	132	18	13	R25	R20	R13	R70	9

Material	Surface Treatment	Color
SS400	uni-chrome coating	white

- Parallel Shaft (Performance Table/Dimension)
- Gearmotor with Brake
- Water-resistant, Outdoor Gearmotor with Brake
- Gearmotor with Clutch/Brake
- Reducer (Double Shaft)
- S-Type Reducer
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# FS • F3S-Type Torque Arm

## F3S Type (Hollow Shaft) • Torque Arm (Option)



### Specificaiton

Frame Number	Name of product	Capacity	Reduction Ratio	A	B	C	D	E	F	G	H	I	J	K	T	Round Weight (kg)
20	TAF3S-20-2	0.1 kW	1 / 5 ~ 1 / 60	53.5	23.5	52	10.5				R10.5	R11	11	9	3.2	0.1
25	TAF3S-25-2	0.2 kW	1 / 5 ~ 1 / 60	60	27	61	10.5	16.5	43.5	R37	R10.5	R15	11	9	3.2	0.2
	TAF3S-25-3	0.1 kW	1 / 80 ~ 1 / 240	69.5	17.5	61	10.5	26	43.5	R37	R10.5	R 6.5	11	11	4.5	0.2
30	TAF3S-30-2	0.4 kW	1 / 5 ~ 1 / 60	69.5	26.5	70	10.5	21.5	48	R41.5	R10.5	R15	11	11	4.5	0.3
	TAF3S-30-3	0.1 kW	1 / 300 ~ 1 / 375	78	14	70	12	32	46	R41.5	R12	R16.5	13.5	13.5	6	0.4
		0.2 kW	1 / 80 ~ 1 / 240													
35	TAF3S-35-2	0.75kW	1 / 5 ~ 1 / 80	80.5	31.5	94	12	24.5	56	R46.5	R12	R18	13.5	13.5	6	0.6
		0.1 kW	1 / 450 ~ 1 / 750													
	TAF3S-35-3	0.2 kW	1 / 300 ~ 1 / 375	97	11	94	15	43	54	R46.5	R15	R22.5	17.5	17.5	9	1.2
		0.4 kW	1 / 80 ~ 1 / 240													
45	TAF3S-45-2	1.5 kW	1 / 5 ~ 1 / 60	103.5	42.5	110	15				R15	R20	17.5	17.5	9	1.4
		2.2 kW	1 / 5 ~ 1 / 30													
	TAF3S-45-3	0.1 kW	1 / 900 ~ 1 / 1200	118	20	110	18.5	49	69	R54	R18.5	R28.5	22	22	9	1.7
		0.2 kW	1 / 450 ~ 1 / 750													
		0.4 kW	1 / 300 ~ 1 / 375													
		0.75kW	1 / 80 ~ 1 / 2400													
50	TAF3S-50-2	2.2 kW	1 / 40 ~ 1 / 60	136	44	140	15				R15	R20	17.5	17.5	9	2.1
55	TAF3S-55-3	0.1 kW	1 / 1500	146	70	160	18.5				R18.5	R28.5	20.5	20.5	12	3.6
		0.2 kW	1 / 900 ~ 1 / 1200													
		0.4 kW	1 / 450 ~ 1 / 600													
		0.75kW	1 / 300													
		1.5 kW	1 / 80 ~ 1 / 240													
		2.2 kW	1 / 80 ~ 1 / 120													

Material	Surface Treatment	Color
SS400	uni-chrome coating	white

## Overhung Load (O.H.L.) on a Hollow Shaft

### Designing the Torque Arm

In case customer does not use our optional torque arm and use their manufactured torque arm as shown in the Figure-8, the distance between the center of the output shaft and the fixing point(r) can be calculated with the following formulas:

SI Unit

$$r(\text{mm}) = \frac{\text{Actual load torque}(\text{N}\cdot\text{m}) \times 1000}{\text{Allowable O.H.L.}(\text{N}) - 9.8 \times \text{Mass of the reducer}(\text{kg})}$$

Gravimetric Unit

$$r(\text{mm}) = \frac{\text{Actual load torque}(\text{kgf}\cdot\text{m}) \times 1000}{\text{Allowable O.H.L.}(\text{kgf}) - \text{Weight of the reducer}(\text{kgf})}$$

In case of using the torque arm as shown in the Figure-9, the distance between the center of the output shaft and the fixing point(r) can be calculated with the following formulas:

SI Unit

$$r(\text{mm}) = \frac{\text{Actual load torque}(\text{N}\cdot\text{m}) \times (\text{A} + \text{M}) \times 1000}{\{\text{Allowable O.H.L.}(\text{N}) - 9.8 \times \text{Mass of the reducer}(\text{kg})\} \times (\text{A} + 20)}$$

Gravimetric Unit

$$r(\text{mm}) = \frac{\text{Actual load torque}(\text{kgf}\cdot\text{m}) \times (\text{A} + \text{M}) \times 1000}{\{\text{Allowable O.H.L.}(\text{kgf}) - \text{Weight of the reducer}(\text{kgf})\} \times (\text{A} + 20)}$$

Note ) Refer to the table below for "A".

Ratio	A( mm )
20	68.5
25	84.5
30	91
35	98
45	113
55	150

Figure-8

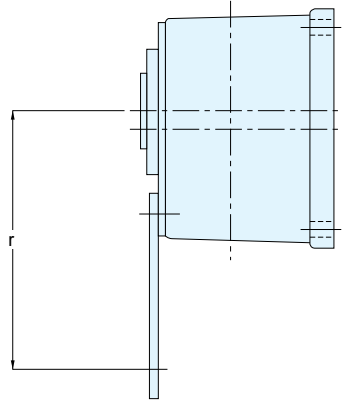
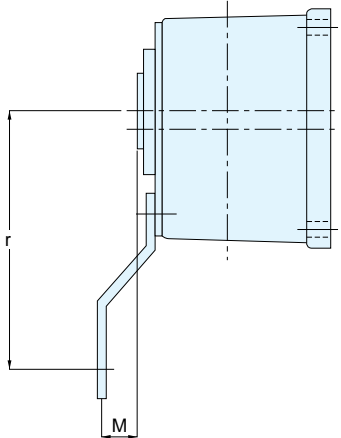


Figure-9



Note ) For the thickness of torque arm, refer to the "Torque Arm(Optional)" in page E61.

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